

# Part IB — Linear Algebra

## Theorems

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These notes are not endorsed by the lecturers, and I have modified them (often significantly) after lectures. They are nowhere near accurate representations of what was actually lectured, and in particular, all errors are almost surely mine.

Definition of a vector space (over  $\mathbb{R}$  or  $\mathbb{C}$ ), subspaces, the space spanned by a subset. Linear independence, bases, dimension. Direct sums and complementary subspaces. [3]

Linear maps, isomorphisms. Relation between rank and nullity. The space of linear maps from  $U$  to  $V$ , representation by matrices. Change of basis. Row rank and column rank. [4]

Determinant and trace of a square matrix. Determinant of a product of two matrices and of the inverse matrix. Determinant of an endomorphism. The adjugate matrix. [3]

Eigenvalues and eigenvectors. Diagonal and triangular forms. Characteristic and minimal polynomials. Cayley-Hamilton Theorem over  $\mathbb{C}$ . Algebraic and geometric multiplicity of eigenvalues. Statement and illustration of Jordan normal form. [4]

Dual of a finite-dimensional vector space, dual bases and maps. Matrix representation, rank and determinant of dual map. [2]

Bilinear forms. Matrix representation, change of basis. Symmetric forms and their link with quadratic forms. Diagonalisation of quadratic forms. Law of inertia, classification by rank and signature. Complex Hermitian forms. [4]

Inner product spaces, orthonormal sets, orthogonal projection,  $V = W \oplus W^\perp$ . Gram-Schmidt orthogonalisation. Adjoint. Diagonalisation of Hermitian matrices. Orthogonality of eigenvectors and properties of eigenvalues. [4]

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## 0 Introduction

# 1 Vector spaces

## 1.1 Definitions and examples

**Proposition.** In any vector space  $V$ ,  $0\mathbf{v} = \mathbf{0}$  for all  $\mathbf{v} \in V$ , and  $(-1)\mathbf{v} = -\mathbf{v}$ , where  $-\mathbf{v}$  is the additive inverse of  $\mathbf{v}$ .

**Proposition.** Let  $U, W$  be subspaces of  $V$ . Then  $U + W$  and  $U \cap W$  are subspaces.

## 1.2 Linear independence, bases and the Steinitz exchange lemma

**Lemma.**  $S \subseteq V$  is linearly dependent if and only if there are distinct  $\mathbf{s}_0, \dots, \mathbf{s}_n \in S$  and  $\lambda_1, \dots, \lambda_n \in \mathbb{F}$  such that

$$\sum_{i=1}^n \lambda_i \mathbf{s}_i = \mathbf{s}_0.$$

**Proposition.** If  $S = \{\mathbf{e}_1, \dots, \mathbf{e}_n\}$  is a subset of  $V$  over  $\mathbb{F}$ , then it is a basis if and only if every  $\mathbf{v} \in V$  can be written uniquely as a finite linear combination of elements in  $S$ , i.e. as

$$\mathbf{v} = \sum_{i=1}^n \lambda_i \mathbf{e}_i.$$

**Theorem** (Steinitz exchange lemma). Let  $V$  be a vector space over  $\mathbb{F}$ , and  $S = \{\mathbf{e}_1, \dots, \mathbf{e}_n\}$  a finite linearly independent subset of  $V$ , and  $T$  a spanning subset of  $V$ . Then there is some  $T' \subseteq T$  of order  $n$  such that  $(T \setminus T') \cup S$  still spans  $V$ . In particular,  $|T| \geq n$ .

**Corollary.** Let  $\{\mathbf{e}_1, \dots, \mathbf{e}_n\}$  be a linearly independent subset of  $V$ , and suppose  $\{\mathbf{f}_1, \dots, \mathbf{f}_m\}$  spans  $V$ . Then there is a re-ordering of the  $\{\mathbf{f}_i\}$  such that  $\{\mathbf{e}_1, \dots, \mathbf{e}_n, \mathbf{f}_{n+1}, \dots, \mathbf{f}_m\}$  spans  $V$ .

**Corollary.** Suppose  $V$  is a vector space over  $\mathbb{F}$  with a basis of order  $n$ . Then

- (i) Every basis of  $V$  has order  $n$ .
- (ii) Any linearly independent set of order  $n$  is a basis.
- (iii) Every spanning set of order  $n$  is a basis.
- (iv) Every finite spanning set contains a basis.
- (v) Every linearly independent subset of  $V$  can be extended to basis.

**Lemma.** If  $V$  is a finite dimensional vector space over  $\mathbb{F}$ ,  $U \subseteq V$  is a proper subspace, then  $U$  is finite dimensional and  $\dim U < \dim V$ .

**Proposition.** If  $U, W$  are subspaces of a finite dimensional vector space  $V$ , then

$$\dim(U + W) = \dim U + \dim W - \dim(U \cap W).$$

**Proposition.** If  $V$  is a finite dimensional vector space over  $\mathbb{F}$  and  $U \subseteq V$  is a subspace, then

$$\dim V = \dim U + \dim V/U.$$

### 1.3 Direct sums

## 2 Linear maps

### 2.1 Definitions and examples

**Lemma.** If  $U$  and  $V$  are vector spaces over  $\mathbb{F}$  and  $\alpha : U \rightarrow V$ , then  $\alpha$  is an isomorphism iff  $\alpha$  is a bijective linear map.

**Proposition.** Let  $\alpha : U \rightarrow V$  be an  $\mathbb{F}$ -linear map. Then

- (i) If  $\alpha$  is injective and  $S \subseteq U$  is linearly independent, then  $\alpha(S)$  is linearly independent in  $V$ .
- (ii) If  $\alpha$  is surjective and  $S \subseteq U$  spans  $U$ , then  $\alpha(S)$  spans  $V$ .
- (iii) If  $\alpha$  is an isomorphism and  $S \subseteq U$  is a basis, then  $\alpha(S)$  is a basis for  $V$ .

**Corollary.** If  $U$  and  $V$  are finite-dimensional vector spaces over  $\mathbb{F}$  and  $\alpha : U \rightarrow V$  is an isomorphism, then  $\dim U = \dim V$ .

**Proposition.** Suppose  $V$  is a  $\mathbb{F}$ -vector space of dimension  $n < \infty$ . Then writing  $\mathbf{e}_1, \dots, \mathbf{e}_n$  for the standard basis of  $\mathbb{F}^n$ , there is a bijection

$$\Phi : \{\text{isomorphisms } \mathbb{F}^n \rightarrow V\} \rightarrow \{(\text{ordered}) \text{ basis } (\mathbf{v}_1, \dots, \mathbf{v}_n) \text{ for } V\},$$

defined by

$$\alpha \mapsto (\alpha(\mathbf{e}_1), \dots, \alpha(\mathbf{e}_n)).$$

### 2.2 Linear maps and matrices

**Proposition.** Suppose  $U, V$  are vector spaces over  $\mathbb{F}$  and  $S = \{\mathbf{e}_1, \dots, \mathbf{e}_n\}$  is a basis for  $U$ . Then every function  $f : S \rightarrow V$  extends uniquely to a linear map  $U \rightarrow V$ .

**Corollary.** If  $U$  and  $V$  are finite-dimensional vector spaces over  $\mathbb{F}$  with bases  $(\mathbf{e}_1, \dots, \mathbf{e}_m)$  and  $(\mathbf{f}_1, \dots, \mathbf{f}_n)$  respectively, then there is a bijection

$$\text{Mat}_{n,m}(\mathbb{F}) \rightarrow \mathcal{L}(U, V),$$

sending  $A$  to the unique linear map  $\alpha$  such that  $\alpha(\mathbf{e}_i) = \sum a_{ji} \mathbf{f}_j$ .

**Proposition.** Suppose  $U, V, W$  are finite-dimensional vector spaces over  $\mathbb{F}$  with bases  $R = (\mathbf{u}_1, \dots, \mathbf{u}_r)$ ,  $S = (\mathbf{v}_1, \dots, \mathbf{v}_s)$  and  $T = (\mathbf{w}_1, \dots, \mathbf{w}_t)$  respectively.

If  $\alpha : U \rightarrow V$  and  $\beta : V \rightarrow W$  are linear maps represented by  $A$  and  $B$  respectively (with respect to  $R, S$  and  $T$ ), then  $\beta\alpha$  is linear and represented by  $BA$  with respect to  $R$  and  $T$ .

### 2.3 The first isomorphism theorem and the rank-nullity theorem

**Theorem** (First isomorphism theorem). Let  $\alpha : U \rightarrow V$  be a linear map. Then  $\ker \alpha$  and  $\text{im } \alpha$  are subspaces of  $U$  and  $V$  respectively. Moreover,  $\alpha$  induces an isomorphism

$$\begin{aligned} \bar{\alpha} : U / \ker \alpha &\rightarrow \text{im } \alpha \\ (\mathbf{u} + \ker \alpha) &\mapsto \alpha(\mathbf{u}) \end{aligned}$$

**Corollary** (Rank-nullity theorem). If  $\alpha : U \rightarrow V$  is a linear map and  $U$  is finite-dimensional, then

$$r(\alpha) + n(\alpha) = \dim U.$$

**Proposition.** If  $\alpha : U \rightarrow V$  is a linear map between finite-dimensional vector spaces over  $\mathbb{F}$ , then there are bases  $(\mathbf{e}_1, \dots, \mathbf{e}_m)$  for  $U$  and  $(\mathbf{f}_1, \dots, \mathbf{f}_n)$  for  $V$  such that  $\alpha$  is represented by the matrix

$$\begin{pmatrix} I_r & 0 \\ 0 & 0 \end{pmatrix},$$

where  $r = r(\alpha)$  and  $I_r$  is the  $r \times r$  identity matrix.

In particular,  $r(\alpha) + n(\alpha) = \dim U$ .

**Corollary.** Suppose  $\alpha : U \rightarrow V$  is a linear map between vector spaces over  $\mathbb{F}$  both of dimension  $n < \infty$ . Then the following are equivalent

- (i)  $\alpha$  is injective;
- (ii)  $\alpha$  is surjective;
- (iii)  $\alpha$  is an isomorphism.

**Lemma.** Let  $A \in M_{n,n}(\mathbb{F}) = M_n(\mathbb{F})$  be a square matrix. The following are equivalent

- (i) There exists  $B \in M_n(\mathbb{F})$  such that  $BA = I_n$ .
- (ii) There exists  $C \in M_n(\mathbb{F})$  such that  $AC = I_n$ .

If these hold, then  $B = C$ . We call  $A$  *invertible* or *non-singular*, and write  $A^{-1} = B = C$ .

## 2.4 Change of basis

**Theorem.** Suppose that  $(\mathbf{e}_1, \dots, \mathbf{e}_m)$  and  $(\mathbf{u}_1, \dots, \mathbf{u}_m)$  are basis for a finite-dimensional vector space  $U$  over  $\mathbb{F}$ , and  $(\mathbf{f}_1, \dots, \mathbf{f}_n)$  and  $(\mathbf{v}_1, \dots, \mathbf{v}_n)$  are basis of a finite-dimensional vector space  $V$  over  $\mathbb{F}$ .

Let  $\alpha : U \rightarrow V$  be a linear map represented by a matrix  $A$  with respect to  $(\mathbf{e}_i)$  and  $(\mathbf{f}_i)$  and by  $B$  with respect to  $(\mathbf{u}_i)$  and  $(\mathbf{v}_i)$ . Then

$$B = Q^{-1}AP,$$

where  $P$  and  $Q$  are given by

$$\mathbf{u}_i = \sum_{k=1}^m P_{ki} \mathbf{e}_k, \quad \mathbf{v}_i = \sum_{k=1}^n Q_{ki} \mathbf{f}_k.$$

**Corollary.** If  $A \in \text{Mat}_{n,m}(\mathbb{F})$ , then there exists invertible matrices  $P \in \text{GL}_m(\mathbb{F}), Q \in \text{GL}_n(\mathbb{F})$  so that

$$Q^{-1}AP = \begin{pmatrix} I_r & 0 \\ 0 & 0 \end{pmatrix}$$

for some  $0 \leq r \leq \min(m, n)$ .

**Theorem.** If  $A \in \text{Mat}_{n,m}(\mathbb{F})$ , then  $r(A) = r(A^T)$ , i.e. the row rank is equivalent to the column rank.

## 2.5 Elementary matrix operations

**Proposition.** If  $A \in \text{Mat}_{n,m}(\mathbb{F})$ , then there exists invertible matrices  $P \in \text{GL}_m(\mathbb{F})$ ,  $Q \in \text{GL}_n(\mathbb{F})$  so that

$$Q^{-1}AP = \begin{pmatrix} I_r & 0 \\ 0 & 0 \end{pmatrix}$$

for some  $0 \leq r \leq \min(m, n)$ .



### 3 Duality

#### 3.1 Dual space

**Lemma.** If  $V$  is a finite-dimensional vector space over  $f$  with basis  $(\mathbf{e}_1, \dots, \mathbf{e}_n)$ , then there is a basis  $(\varepsilon_1, \dots, \varepsilon_n)$  for  $V^*$  (called the *dual basis* to  $(\mathbf{e}_1, \dots, \mathbf{e}_n)$ ) such that

$$\varepsilon_i(\mathbf{e}_j) = \delta_{ij}.$$

**Corollary.** If  $V$  is finite dimensional, then  $\dim V = \dim V^*$ .

**Proposition.** Let  $V$  be a finite-dimensional vector space over  $\mathbb{F}$  with bases  $(\mathbf{e}_1, \dots, \mathbf{e}_n)$  and  $(\mathbf{f}_1, \dots, \mathbf{f}_n)$ , and that  $P$  is the change of basis matrix so that

$$\mathbf{f}_i = \sum_{k=1}^n P_{ki} \mathbf{e}_k.$$

Let  $(\varepsilon_1, \dots, \varepsilon_n)$  and  $(\eta_1, \dots, \eta_n)$  be the corresponding dual bases so that

$$\varepsilon_i(\mathbf{e}_j) = \delta_{ij} = \eta_i(\mathbf{f}_j).$$

Then the change of basis matrix from  $(\varepsilon_1, \dots, \varepsilon_n)$  to  $(\eta_1, \dots, \eta_n)$  is  $(P^{-1})^T$ , i.e.

$$\varepsilon_i = \sum_{\ell=1}^n P_{\ell i}^T \eta_\ell.$$

**Proposition.** Let  $V$  be a vector space over  $\mathbb{F}$  and  $U$  a subspace. Then

$$\dim U + \dim U^0 = \dim V.$$

#### 3.2 Dual maps

**Proposition.** Let  $\alpha \in \mathcal{L}(V, W)$  be a linear map. Then  $\alpha^* \in \mathcal{L}(W^*, V^*)$  is a linear map.

**Proposition.** Let  $V, W$  be finite-dimensional vector spaces over  $\mathbb{F}$  and  $\alpha : V \rightarrow W$  be a linear map. Let  $(\mathbf{e}_1, \dots, \mathbf{e}_n)$  be a basis for  $V$  and  $(\mathbf{f}_1, \dots, \mathbf{f}_m)$  be a basis for  $W$ ;  $(\varepsilon_1, \dots, \varepsilon_n)$  and  $(\eta_1, \dots, \eta_m)$  the corresponding dual bases.

Suppose  $\alpha$  is represented by  $A$  with respect to  $(\mathbf{e}_i)$  and  $(\mathbf{f}_i)$  for  $V$  and  $W$ . Then  $\alpha^*$  is represented by  $A^T$  with respect to the corresponding dual bases.

**Lemma.** Let  $\alpha \in \mathcal{L}(V, W)$  with  $V, W$  finite dimensional vector spaces over  $\mathbb{F}$ . Then

- (i)  $\ker \alpha^* = (\operatorname{im} \alpha)^0$ .
- (ii)  $r(\alpha) = r(\alpha^*)$  (which is another proof that row rank is equal to column rank).
- (iii)  $\operatorname{im} \alpha^* = (\ker \alpha)^0$ .

**Lemma.** Let  $V$  be a vector space over  $\mathbb{F}$ . Then there is a linear map  $\operatorname{ev} : V \rightarrow (V^*)^*$  given by

$$\operatorname{ev}(\mathbf{v})(\theta) = \theta(\mathbf{v}).$$

We call this the *evaluation* map.

**Lemma.** If  $V$  is finite-dimensional, then  $\text{ev} : V \rightarrow V^{**}$  is an isomorphism.

**Lemma.** Let  $V, W$  be finite-dimensional vector spaces over  $\mathbb{F}$  after identifying  $(V$  and  $V^{**})$  and  $(W$  and  $W^{**})$  by the evaluation map. Then we have

- (i) If  $U \leq V$ , then  $U^{00} = U$ .
- (ii) If  $\alpha \in \mathcal{L}(V, W)$ , then  $\alpha^{**} = \alpha$ .

**Proposition.** Let  $V$  be a finite-dimensional vector space  $\mathbb{F}$  and  $U_1, U_2$  are subspaces of  $V$ . Then we have

- (i)  $(U_1 + U_2)^0 = U_1^0 \cap U_2^0$
- (ii)  $(U_1 \cap U_2)^0 = U_1^0 + U_2^0$

## 4 Bilinear forms I

**Proposition.** Suppose  $(\mathbf{e}_1, \dots, \mathbf{e}_n)$  and  $(\mathbf{v}_1, \dots, \mathbf{v}_n)$  are basis for  $V$  such that

$$\mathbf{v}_i = \sum P_{ki} \mathbf{e}_k \text{ for all } i = 1, \dots, n;$$

and  $(\mathbf{f}_1, \dots, \mathbf{f}_m)$  and  $(\mathbf{w}_1, \dots, \mathbf{w}_m)$  are bases for  $W$  such that

$$\mathbf{w}_j = \sum Q_{\ell j} \mathbf{f}_\ell \text{ for all } j = 1, \dots, m.$$

Let  $\psi : V \times W \rightarrow \mathbb{F}$  be a bilinear form represented by  $A$  with respect to  $(\mathbf{e}_1, \dots, \mathbf{e}_n)$  and  $(\mathbf{f}_1, \dots, \mathbf{f}_m)$ , and by  $B$  with respect to the bases  $(\mathbf{v}_1, \dots, \mathbf{v}_n)$  and  $(\mathbf{w}_1, \dots, \mathbf{w}_m)$ . Then

$$B = P^T A Q.$$

**Lemma.** Let  $(\varepsilon_1, \dots, \varepsilon_n)$  be a basis for  $V^*$  dual to  $(\mathbf{e}_1, \dots, \mathbf{e}_n)$  of  $V$ ;  $(\eta_1, \dots, \eta_m)$  be a basis for  $W^*$  dual to  $(\mathbf{f}_1, \dots, \mathbf{f}_m)$  of  $W$ .

If  $A$  represents  $\psi$  with respect to  $(\mathbf{e}_1, \dots, \mathbf{e}_n)$  and  $(\mathbf{f}_1, \dots, \mathbf{f}_m)$ , then  $A$  also represents  $\psi_R$  with respect to  $(\mathbf{f}_1, \dots, \mathbf{f}_m)$  and  $(\varepsilon_1, \dots, \varepsilon_n)$ ; and  $A^T$  represents  $\psi_L$  with respect to  $(\mathbf{e}_1, \dots, \mathbf{e}_n)$  and  $(\eta_1, \dots, \eta_m)$ .

**Lemma.** Let  $V$  and  $W$  be finite-dimensional vector spaces over  $\mathbb{F}$  with bases  $(\mathbf{e}_1, \dots, \mathbf{e}_n)$  and  $(\mathbf{f}_1, \dots, \mathbf{f}_m)$  be their basis respectively.

Let  $\psi : V \times W \rightarrow \mathbb{F}$  be a bilinear form represented by  $A$  with respect to these bases. Then  $\psi$  is non-degenerate if and only if  $A$  is (square and) invertible. In particular,  $V$  and  $W$  have the same dimension.

## 5 Determinants of matrices

**Lemma.**  $\det A = \det A^T$ .

**Lemma.** If  $A$  is an upper triangular matrix, i.e.

$$A = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ 0 & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & a_{nn} \end{pmatrix}$$

Then

$$\det A = \prod_{i=1}^n a_{ii}.$$

**Lemma.**  $\det A$  is a volume form.

**Lemma.** Let  $d$  be a volume form on  $\mathbb{F}^n$ . Then swapping two entries changes the sign, i.e.

$$d(\mathbf{v}_1, \dots, \mathbf{v}_i, \dots, \mathbf{v}_j, \dots, \mathbf{v}_n) = -d(\mathbf{v}_1, \dots, \mathbf{v}_j, \dots, \mathbf{v}_i, \dots, \mathbf{v}_n).$$

**Corollary.** If  $\sigma \in S_n$ , then

$$d(\mathbf{v}_{\sigma(1)}, \dots, \mathbf{v}_{\sigma(n)}) = \varepsilon(\sigma)d(\mathbf{v}_1, \dots, \mathbf{v}_n)$$

for any  $\mathbf{v}_i \in \mathbb{F}^n$ .

**Theorem.** Let  $d$  be any volume form on  $\mathbb{F}^n$ , and let  $A = (A^{(1)} \dots A^{(n)}) \in \text{Mat}_n(\mathbb{F})$ . Then

$$d(A^{(1)}, \dots, A^{(n)}) = (\det A)d(\mathbf{e}_1, \dots, \mathbf{e}_n),$$

where  $\{\mathbf{e}_1, \dots, \mathbf{e}_n\}$  is the standard basis.

**Theorem.** Let  $A, B \in \text{Mat}_n(\mathbb{F})$ . Then  $\det(AB) = \det(A)\det(B)$ .

**Corollary.** If  $A \in \text{Mat}_n(\mathbb{F})$  is invertible, then  $\det A \neq 0$ . In fact, when  $A$  is invertible, then  $\det(A^{-1}) = (\det A)^{-1}$ .

**Theorem.** Let  $A \in \text{Mat}_n(\mathbb{F})$ . Then the following are equivalent:

- (i)  $A$  is invertible.
- (ii)  $\det A \neq 0$ .
- (iii)  $r(A) = n$ .

**Lemma.** Let  $A \in \text{Mat}_n(\mathbb{F})$ . Then

- (i) We can expand  $\det A$  along the  $j$ th column by

$$\det A = \sum_{i=1}^n (-1)^{i+j} A_{ij} \det \hat{A}_{ij}.$$

(ii) We can expand  $\det A$  along the  $i$ th row by

$$\det A = \sum_{j=1}^n (-1)^{i+j} A_{ij} \det \hat{A}_{ij}.$$

**Theorem.** If  $A \in \text{Mat}_n(\mathbb{F})$ , then  $A(\text{adj } A) = (\det A)I_n = (\text{adj } A)A$ . In particular, if  $\det A \neq 0$ , then

$$A^{-1} = \frac{1}{\det A} \text{adj } A.$$

**Lemma.** Let  $A, B$  be square matrices. Then for any  $C$ , we have

$$\det \begin{pmatrix} A & C \\ 0 & B \end{pmatrix} = (\det A)(\det B).$$

**Corollary.**

$$\det \begin{pmatrix} A_1 & & & \text{stuff} \\ & A_2 & & \\ & & \ddots & \\ 0 & & & A_n \end{pmatrix} = \prod_{i=1}^n \det A_i$$

## 6 Endomorphisms

### 6.1 Invariants

**Lemma.** Suppose  $(\mathbf{e}_1, \dots, \mathbf{e}_n)$  and  $(\mathbf{f}_1, \dots, \mathbf{f}_n)$  are bases for  $V$  and  $\alpha \in \text{End}(V)$ . If  $A$  represents  $\alpha$  with respect to  $(\mathbf{e}_1, \dots, \mathbf{e}_n)$  and  $B$  represents  $\alpha$  with respect to  $(\mathbf{f}_1, \dots, \mathbf{f}_n)$ , then

$$B = P^{-1}AP,$$

where  $P$  is given by

$$\mathbf{f}_i = \sum_{j=1}^n P_{ji} \mathbf{e}_j.$$

**Lemma.**

(i) If  $A \in \text{Mat}_{m,n}(\mathbb{F})$  and  $B \in \text{Mat}_{n,m}(\mathbb{F})$ , then

$$\text{tr } AB = \text{tr } BA.$$

(ii) If  $A, B \in \text{Mat}_n(\mathbb{F})$  are similar, then  $\text{tr } A = \text{tr } B$ .

(iii) If  $A, B \in \text{Mat}_n(\mathbb{F})$  are similar, then  $\det A = \det B$ .

**Lemma.** If  $A$  and  $B$  are similar, then they have the same characteristic polynomial.

**Lemma.** Let  $\alpha \in \text{End}(V)$  and  $\lambda_1, \dots, \lambda_k$  distinct eigenvalues of  $\alpha$ . Then

$$E(\lambda_1) + \dots + E(\lambda_k) = \bigoplus_{i=1}^k E(\lambda_i)$$

is a direct sum.

**Theorem.** Let  $\alpha \in \text{End}(V)$  and  $\lambda_1, \dots, \lambda_k$  be distinct eigenvalues of  $\alpha$ . Write  $E_i$  for  $E(\lambda_i)$ . Then the following are equivalent:

- (i)  $\alpha$  is diagonalizable.
- (ii)  $V$  has a basis of eigenvectors for  $\alpha$ .
- (iii)  $V = \bigoplus_{i=1}^k E_i$ .
- (iv)  $\dim V = \sum_{i=1}^k \dim E_i$ .

### 6.2 The minimal polynomial

#### 6.2.1 Aside on polynomials

**Lemma** (Polynomial division). If  $f, g \in \mathbb{F}[t]$  (and  $g \neq 0$ ), then there exists  $q, r \in \mathbb{F}[t]$  with  $\deg r < \deg g$  such that

$$f = qg + r.$$

**Lemma.** If  $\lambda \in \mathbb{F}$  is a root of  $f$ , i.e.  $f(\lambda) = 0$ , then there is some  $g$  such that

$$f(t) = (t - \lambda)g(t).$$

**Lemma.** A non-zero polynomial  $f \in \mathbb{F}[t]$  has at most  $\deg f$  roots, counted with multiplicity.

**Corollary.** Let  $f, g \in \mathbb{F}[t]$  have degree  $< n$ . If there are  $\lambda_1, \dots, \lambda_n$  distinct such that  $f(\lambda_i) = g(\lambda_i)$  for all  $i$ , then  $f = g$ .

**Corollary.** If  $\mathbb{F}$  is infinite, then  $f$  and  $g$  are equal if and only if they agree on all points.

**Theorem** (The fundamental theorem of algebra). Every non-constant polynomial over  $\mathbb{C}$  has a root in  $\mathbb{C}$ .

### 6.2.2 Minimal polynomial

**Theorem** (Diagonalizability theorem). Suppose  $\alpha \in \text{End}(V)$ . Then  $\alpha$  is diagonalizable if and only if there exists non-zero  $p(t) \in \mathbb{F}[t]$  such that  $p(\alpha) = 0$ , and  $p(t)$  can be factored as a product of *distinct* linear factors.

**Lemma.** Let  $\alpha \in \text{End}(V)$ , and  $p \in \mathbb{F}[t]$ . Then  $p(\alpha) = 0$  if and only if  $M_\alpha(t)$  is a factor of  $p(t)$ . In particular,  $M_\alpha$  is unique.

**Theorem** (Diagonalizability theorem 2.0). Let  $\alpha \in \text{End}(V)$ . Then  $\alpha$  is diagonalizable if and only if  $M_\alpha(t)$  is a product of its distinct linear factors.

**Theorem.** Let  $\alpha, \beta \in \text{End}(V)$  be both diagonalizable. Then  $\alpha$  and  $\beta$  are simultaneously diagonalizable (i.e. there exists a basis with respect to which both are diagonal) if and only if  $\alpha\beta = \beta\alpha$ .

## 6.3 The Cayley-Hamilton theorem

**Theorem** (Cayley-Hamilton theorem). Let  $V$  be a finite-dimensional vector space and  $\alpha \in \text{End}(V)$ . Then  $\chi_\alpha(\alpha) = 0$ , i.e.  $M_\alpha(t) \mid \chi_\alpha(t)$ . In particular,  $\deg M_\alpha \leq n$ .

**Lemma.** An endomorphism  $\alpha$  is triangulable if and only if  $\chi_\alpha(t)$  can be written as a product of linear factors, not necessarily distinct. In particular, if  $\mathbb{F} = \mathbb{C}$  (or any algebraically closed field), then every endomorphism is triangulable.

**Theorem** (Cayley-Hamilton theorem). Let  $V$  be a finite-dimensional vector space and  $\alpha \in \text{End}(V)$ . Then  $\chi_\alpha(\alpha) = 0$ , i.e.  $M_\alpha(t) \mid \chi_\alpha(t)$ . In particular,  $\deg M_\alpha \leq n$ .

**Lemma.** Let  $\alpha \in \text{End}(V), \lambda \in \mathbb{F}$ . Then the following are equivalent:

- (i)  $\lambda$  is an eigenvalue of  $\alpha$ .
- (ii)  $\lambda$  is a root of  $\chi_\alpha(t)$ .
- (iii)  $\lambda$  is a root of  $M_\alpha(t)$ .

## 6.4 Multiplicities of eigenvalues and Jordan normal form

**Lemma.** If  $\lambda$  is an eigenvalue of  $\alpha$ , then

- (i)  $1 \leq g_\lambda \leq a_\lambda$
- (ii)  $1 \leq c_\lambda \leq a_\lambda$ .

**Lemma.** Suppose  $\mathbb{F} = \mathbb{C}$  and  $\alpha \in \text{End}(V)$ . Then the following are equivalent:

- (i)  $\alpha$  is diagonalizable.
- (ii)  $g_\lambda = a_\lambda$  for all eigenvalues of  $\alpha$ .
- (iii)  $c_\lambda = 1$  for all  $\lambda$ .

**Theorem** (Jordan normal form theorem). Every matrix  $A \in \text{Mat}_n(\mathbb{C})$  is similar to a matrix in Jordan normal form. Moreover, this Jordan normal form matrix is unique up to permutation of the blocks.

**Theorem.** Let  $\alpha \in \text{End}(V)$ , and  $A$  in Jordan normal form representing  $\alpha$ . Then the number of Jordan blocks  $J_n(\lambda)$  in  $A$  with  $n \geq r$  is

$$n((\alpha - \lambda I)^r) - n((\alpha - \lambda I)^{r-1}).$$

**Theorem** (Generalized eigenspace decomposition). Let  $V$  be a finite-dimensional vector space  $\mathbb{C}$  such that  $\alpha \in \text{End}(V)$ . Suppose that

$$M_\alpha(t) = \prod_{i=1}^k (t - \lambda_i)^{c_i},$$

with  $\lambda_1, \dots, \lambda_k \in \mathbb{C}$  distinct. Then

$$V = V_1 \oplus \dots \oplus V_k,$$

where  $V_i = \ker((\alpha - \lambda_i I)^{c_i})$  is the *generalized eigenspace*.



## 7 Bilinear forms II

### 7.1 Symmetric bilinear forms and quadratic forms

**Lemma.** Let  $V$  be a finite-dimensional vector space over  $\mathbb{F}$ , and  $\phi : V \times V \rightarrow \mathbb{F}$  is a symmetric bilinear form. Let  $(\mathbf{e}_1, \dots, \mathbf{e}_n)$  be a basis for  $V$ , and let  $M$  be the matrix representing  $\phi$  with respect to this basis, i.e.  $M_{ij} = \phi(\mathbf{e}_i, \mathbf{e}_j)$ . Then  $\phi$  is symmetric if and only if  $M$  is symmetric.

**Lemma.** Let  $V$  is a finite-dimensional vector space, and  $\phi : V \times V \rightarrow \mathbb{F}$  a bilinear form. Let  $(\mathbf{e}_1, \dots, \mathbf{e}_n)$  and  $(\mathbf{f}_1, \dots, \mathbf{f}_n)$  be bases of  $V$  such that

$$\mathbf{f}_i = \sum_{k=1}^n P_{ki} \mathbf{e}_k.$$

If  $A$  represents  $\phi$  with respect to  $(\mathbf{e}_i)$  and  $B$  represents  $\phi$  with respect to  $(\mathbf{f}_i)$ , then

$$B = P^T A P.$$

**Proposition** (Polarization identity). Suppose that  $\text{char } \mathbb{F} \neq 2$ , i.e.  $1 + 1 \neq 0$  on  $\mathbb{F}$  (e.g. if  $\mathbb{F}$  is  $\mathbb{R}$  or  $\mathbb{C}$ ). If  $q : V \rightarrow \mathbb{F}$  is a quadratic form, then there exists a *unique* symmetric bilinear form  $\phi : V \times V \rightarrow \mathbb{F}$  such that

$$q(\mathbf{v}) = \phi(\mathbf{v}, \mathbf{v}).$$

**Theorem.** Let  $V$  be a finite-dimensional vector space over  $\mathbb{F}$ , and  $\phi : V \times V \rightarrow \mathbb{F}$  a symmetric bilinear form. Then there exists a basis  $(\mathbf{e}_1, \dots, \mathbf{e}_n)$  for  $V$  such that  $\phi$  is represented by a diagonal matrix with respect to this basis.

**Theorem.** Let  $\phi$  be a symmetric bilinear form over a complex vector space  $V$ . Then there exists a basis  $(\mathbf{v}_1, \dots, \mathbf{v}_m)$  for  $V$  such that  $\phi$  is represented by

$$\begin{pmatrix} I_r & 0 \\ 0 & 0 \end{pmatrix}$$

with respect to this basis, where  $r = r(\phi)$ .

**Corollary.** Every symmetric  $A \in \text{Mat}_n(\mathbb{C})$  is congruent to a unique matrix of the form

$$\begin{pmatrix} I_r & 0 \\ 0 & 0 \end{pmatrix}.$$

**Theorem.** Let  $\phi$  be a symmetric bilinear form of a finite-dimensional vector space over  $\mathbb{R}$ . Then there exists a basis  $(\mathbf{v}_1, \dots, \mathbf{v}_n)$  for  $V$  such that  $\phi$  is represented

$$\begin{pmatrix} I_p & & \\ & -I_q & \\ & & 0 \end{pmatrix},$$

with  $p + q = r(\phi)$ ,  $p, q \geq 0$ . Equivalently, the corresponding quadratic forms is given by

$$q \left( \sum_{i=1}^n a_i \mathbf{v}_i \right) = \sum_{i=1}^p a_i^2 - \sum_{j=p+1}^{p+q} a_j^2.$$

**Theorem** (Sylvester's law of inertia). Let  $\phi$  be a symmetric bilinear form on a finite-dimensional real vector space  $V$ . Then there exists unique non-negative integers  $p, q$  such that  $\phi$  is represented by

$$\begin{pmatrix} I_p & 0 & 0 \\ 0 & -I_q & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

with respect to some basis.

**Corollary.** Every real symmetric matrix is congruent to precisely one matrix of the form

$$\begin{pmatrix} I_p & 0 & 0 \\ 0 & -I_q & 0 \\ 0 & 0 & 0 \end{pmatrix}.$$

## 7.2 Hermitian form

**Lemma.** Let  $\phi : V \times V \rightarrow \mathbb{C}$  be a sesquilinear form on a finite-dimensional vector space over  $\mathbb{C}$ , and  $(\mathbf{e}_1, \dots, \mathbf{e}_n)$  a basis for  $V$ . Then  $\phi$  is Hermitian if and only if the matrix  $A$  representing  $\phi$  is Hermitian (i.e.  $A = A^\dagger$ ).

**Proposition** (Change of basis). Let  $\phi$  be a Hermitian form on a finite dimensional vector space  $V$ ;  $(\mathbf{e}_1, \dots, \mathbf{e}_n)$  and  $(\mathbf{v}_1, \dots, \mathbf{v}_n)$  are bases for  $V$  such that

$$\mathbf{v}_i = \sum_{k=1}^n P_{ki} \mathbf{e}_k;$$

and  $A, B$  represent  $\phi$  with respect to  $(\mathbf{e}_1, \dots, \mathbf{e}_n)$  and  $(\mathbf{v}_1, \dots, \mathbf{v}_n)$  respectively. Then

$$B = P^\dagger A P.$$

**Lemma** (Polarization identity (again)). A Hermitian form  $\phi$  on  $V$  is determined by the function  $\psi : \mathbf{v} \mapsto \phi(\mathbf{v}, \mathbf{v})$ .

**Theorem** (Hermitian form of Sylvester's law of inertia). Let  $V$  be a finite-dimensional complex vector space and  $\phi$  a hermitian form on  $V$ . Then there exists unique non-negative integers  $p$  and  $q$  such that  $\phi$  is represented by

$$\begin{pmatrix} I_p & 0 & 0 \\ 0 & -I_q & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

with respect to some basis.

## 8 Inner product spaces

### 8.1 Definitions and basic properties

**Theorem** (Cauchy-Schwarz inequality). Let  $V$  be an inner product space and  $\mathbf{v}, \mathbf{w} \in V$ . Then

$$|(\mathbf{v}, \mathbf{w})| \leq \|\mathbf{v}\| \|\mathbf{w}\|.$$

**Corollary** (Triangle inequality). Let  $V$  be an inner product space and  $\mathbf{v}, \mathbf{w} \in V$ . Then

$$\|\mathbf{v} + \mathbf{w}\| \leq \|\mathbf{v}\| + \|\mathbf{w}\|.$$

**Lemma** (Parseval's identity). Let  $V$  be a finite-dimensional inner product space with an orthonormal basis  $\mathbf{v}_1, \dots, \mathbf{v}_n$ , and  $\mathbf{v}, \mathbf{w} \in V$ . Then

$$(\mathbf{v}, \mathbf{w}) = \sum_{i=1}^n \overline{(\mathbf{v}_i, \mathbf{v})} (\mathbf{v}_i, \mathbf{w}).$$

In particular,

$$\|\mathbf{v}\|^2 = \sum_{i=1}^n |(\mathbf{v}_i, \mathbf{v})|^2.$$

### 8.2 Gram-Schmidt orthogonalization

**Theorem** (Gram-Schmidt process). Let  $V$  be an inner product space and  $\mathbf{e}_1, \mathbf{e}_2, \dots$  a linearly independent set. Then we can construct an orthonormal set  $\mathbf{v}_1, \mathbf{v}_2, \dots$  with the property that

$$\langle \mathbf{v}_1, \dots, \mathbf{v}_k \rangle = \langle \mathbf{e}_1, \dots, \mathbf{e}_k \rangle$$

for every  $k$ .

**Corollary.** If  $V$  is a finite-dimensional inner product space, then any orthonormal set can be extended to an orthonormal basis.

**Proposition.** Let  $V$  be a finite-dimensional inner product space, and  $W \leq V$ . Then

$$V = W \perp W^\perp.$$

**Proposition.** Let  $V$  be a finite-dimensional inner product space and  $W \leq V$ . Let  $(\mathbf{e}_1, \dots, \mathbf{e}_k)$  be an orthonormal basis of  $W$ . Let  $\pi$  be the orthonormal projection of  $V$  onto  $W$ , i.e.  $\pi : V \rightarrow W$  is a function that satisfies  $\ker \pi = W^\perp$ ,  $\pi|_W = \text{id}$ . Then

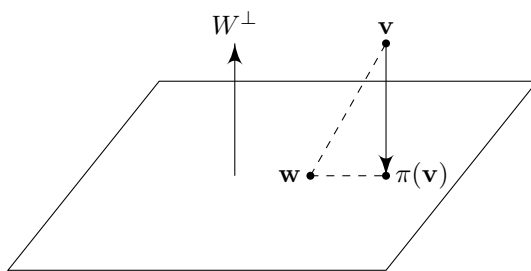
(i)  $\pi$  is given by the formula

$$\pi(\mathbf{v}) = \sum_{i=1}^k (\mathbf{e}_i, \mathbf{v}) \mathbf{e}_i.$$

(ii) For all  $\mathbf{v} \in V, \mathbf{w} \in W$ , we have

$$\|\mathbf{v} - \pi(\mathbf{v})\| \leq \|\mathbf{v} - \mathbf{w}\|,$$

with equality if and only if  $\pi(\mathbf{v}) = \mathbf{w}$ . This says  $\pi(\mathbf{v})$  is the point on  $W$  that is closest to  $\mathbf{v}$ .



### 8.3 Adjoints, orthogonal and unitary maps

**Lemma.** Let  $V$  and  $W$  be finite-dimensional inner product spaces and  $\alpha : V \rightarrow W$  is a linear map. Then there exists a unique linear map  $\alpha^* : W \rightarrow V$  such that

$$(\alpha \mathbf{v}, \mathbf{w}) = (\mathbf{v}, \alpha^* \mathbf{w}) \quad (*)$$

for all  $\mathbf{v} \in V$ ,  $\mathbf{w} \in W$ .

**Lemma.** Let  $V$  be a finite-dimensional space and  $\alpha \in \text{End}(V)$ . Then  $\alpha$  is orthogonal if and only if  $\alpha^{-1} = \alpha^*$ .

**Corollary.**  $\alpha \in \text{End}(V)$  is orthogonal if and only if  $\alpha$  is represented by an orthogonal matrix, i.e. a matrix  $A$  such that  $A^T A = A A^T = I$ , with respect to any orthonormal basis.

**Proposition.** Let  $V$  be a finite-dimensional real inner product space and  $(\mathbf{e}_1, \dots, \mathbf{e}_n)$  is an orthonormal basis of  $V$ . Then there is a bijection

$$\begin{aligned} \text{O}(V) &\rightarrow \{\text{orthonormal basis for } V\} \\ \alpha &\mapsto (\alpha(\mathbf{e}_1), \dots, \alpha(\mathbf{e}_n)). \end{aligned}$$

**Lemma.** Let  $V$  be a finite dimensional complex inner product space and  $\alpha \in \text{End}(V)$ . Then  $\alpha$  is unitary if and only if  $\alpha$  is invertible and  $\alpha^* = \alpha^{-1}$ .

**Corollary.**  $\alpha \in \text{End}(V)$  is unitary if and only if  $\alpha$  is represented by a unitary matrix  $A$  with respect to any orthonormal basis, i.e.  $A^{-1} = A^\dagger$ .

**Proposition.** Let  $V$  be a finite-dimensional complex inner product space. Then there is a bijection

$$\begin{aligned} U(V) &\rightarrow \{\text{orthonormal basis of } V\} \\ \alpha &\mapsto \{\alpha(\mathbf{e}_1), \dots, \alpha(\mathbf{e}_n)\}. \end{aligned}$$

### 8.4 Spectral theory

**Lemma.** Let  $V$  be a finite-dimensional inner product space, and  $\alpha \in \text{End}(V)$  self-adjoint. Then

- (i)  $\alpha$  has a real eigenvalue, and all eigenvalues of  $\alpha$  are real.
- (ii) Eigenvectors of  $\alpha$  with distinct eigenvalues are orthogonal.

**Theorem.** Let  $V$  be a finite-dimensional inner product space, and  $\alpha \in \text{End}(V)$  self-adjoint. Then  $V$  has an orthonormal basis of eigenvectors of  $\alpha$ .

**Corollary.** Let  $V$  be a finite-dimensional vector space and  $\alpha$  self-adjoint. Then  $V$  is the orthogonal (internal) direct sum of its  $\alpha$ -eigenspaces.

**Corollary.** Let  $A \in \text{Mat}_n(\mathbb{R})$  be symmetric. Then there exists an orthogonal matrix  $P$  such that  $P^T A P = P^{-1} A P$  is diagonal.

**Corollary.** Let  $V$  be a finite-dimensional real inner product space and  $\psi : V \times V \rightarrow \mathbb{R}$  a symmetric bilinear form. Then there exists an orthonormal basis  $(\mathbf{v}_1, \dots, \mathbf{v}_n)$  for  $V$  with respect to which  $\psi$  is represented by a diagonal matrix.

**Corollary.** Let  $V$  be a finite-dimensional real vector space and  $\phi, \psi$  symmetric bilinear forms on  $V$  such that  $\phi$  is positive-definite. Then we can find a basis  $(\mathbf{v}_1, \dots, \mathbf{v}_n)$  for  $V$  such that both  $\phi$  and  $\psi$  are represented by diagonal matrices with respect to this basis.

**Corollary.** If  $A, B \in \text{Mat}_n(\mathbb{R})$  are symmetric and  $A$  is positive definite (i.e.  $\mathbf{v}^T A \mathbf{v} > 0$  for all  $\mathbf{v} \in \mathbb{R}^n \setminus \{0\}$ ). Then there exists an invertible matrix  $Q$  such that  $Q^T A Q$  and  $Q^T B Q$  are both diagonal.

**Proposition.**

- (i) If  $A \in \text{Mat}_n(\mathbb{C})$  is Hermitian, then there exists a unitary matrix  $U \in \text{Mat}_n(\mathbb{C})$  such that

$$U^{-1} A U = U^\dagger A U$$

is diagonal.

- (ii) If  $\psi$  is a Hermitian form on a finite-dimensional complex inner product space  $V$ , then there is an orthonormal basis for  $V$  diagonalizing  $\psi$ .
- (iii) If  $\phi, \psi$  are Hermitian forms on a finite-dimensional complex vector space and  $\phi$  is positive definite, then there exists a basis for which  $\phi$  and  $\psi$  are diagonalized.
- (iv) Let  $A, B \in \text{Mat}_n(\mathbb{C})$  be Hermitian, and  $A$  positive definite (i.e.  $\mathbf{v}^\dagger A \mathbf{v} > 0$  for  $\mathbf{v} \in V \setminus \{0\}$ ). Then there exists some invertible  $Q$  such that  $Q^\dagger A Q$  and  $Q^\dagger B Q$  are diagonal.

**Theorem.** Let  $V$  be a finite-dimensional complex vector space and  $\alpha \in U(V)$  be unitary. Then  $V$  has an orthonormal basis of  $\alpha$  eigenvectors.